## Chapter 7

# **Statistical Models**

Recommender systems is inherently statistical. Indeed, the very fact that we discuss the biasvariance tradeoff recognizes the fact that our data are subject to sampling variation, a core statistical notion. In this chapter, we will apply classical statistical estimation methods to a certain *latent variables* model.

## 7.1 The Basic Model

Again, for concreteness, we'll speak in terms of user ratings of movies. Let (U, I) denote a random (user ID, movie ID) pair. Let u and m denote the numbers of users and movies. Denote the user's rating by  $Y_{IJ}$ . The model is additive, postulating that

$$Y_{IJ} = \mu + \alpha_I + \beta_J + \epsilon_{IJ} \tag{7.1}$$

Here  $\mu$  is an unknown constant, the overall population mean over all users and all movies. The numbers  $\alpha_1, \alpha_2, ..., \alpha_u$  and  $\beta_1, \beta_2, ..., \beta_m$  are also unknown constants; think of  $\alpha_i$  to be the tendency of user *i* to give harsher ( $\alpha_i < 0$ ) or more generous ( $\alpha_i > 0$ ) ratings, relative to the general population of users, with a similar situation for the  $\beta_j$  and movies. The  $\epsilon$  term is thought of as the combination of all other affects.

Note that what makes, e.g.,  $\alpha_I$  random above is that I is random, and similarly for the  $\beta_J$  and  $\epsilon_{IJ}$ . The  $\alpha$ ,  $\beta$  and  $\epsilon$  terms are assumed to be statistically independent, each with mean 0.

So, we model a user's rating of a movie as the sum of latent additive user and movie terms, plus a catch-all "everything else" term.<sup>1</sup> The question then becomes how to estimate  $\mu$ , and  $\alpha_1, \alpha_2, ..., \alpha_u$ 

<sup>&</sup>lt;sup>1</sup>What does the word *latent* here mean? Why is  $\mu$  not "latent"? The answer is that it is a tangible quantity;

and  $\beta_1, \beta_2, ..., \beta_m$ , where u and m are the numbers of users and movies in our data. We will present two methods.

## 7.2 Two General Statistical Methods for Parameter Estimation

We'll be using two famous estimation tools from statistics, the Method of Moments and Maximum Likelihood Estimation. We'll introduce those in this section.

#### 7.2.1 Example: Guessing the Number of Coin Tosses

To avoid distracting complexity, consider the following game. I toss a coin until I accumulate a total of r heads. I don't tell you the value of r that I used, only informing you of K, the number of tosses I needed.

It can be shown that

$$P(K = u) = {\binom{u-1}{r-1}} 0.5^u, \ u = r, r+1, \dots$$
(7.2)

Say I play the game 3 times, and I tell you K = 7,10 and 9. What could you do to try to guess r? Notation: We play the game n times, always with the same r, yielding  $K_1, K_2, ..., K_n$ .

#### 7.2.2 The Method of Moments

The moments of a random variable X are the expected values of the powers. E.g.  $E(X^3)$  is called the third moment of X.

If we are trying to estimate s parameters,  $\theta_1, ..., \theta_s$ , we need s moments. We find population expressions for the  $\theta_i$  in terms of the first s moments of the random variable at hand, setting up s equations that match those expressions to the estimated parameters,  $\hat{\theta}_1, ..., \hat{\theta}_s$ , then solve for the latter, then solve for the latter

Here we have just one parameter, r. It can be shown that in the game example,

$$E(K) = \frac{r}{0.5} = 2r \tag{7.3}$$

we all can imagine finding the overall mean for all users and movies, given enough data. By contrast, the  $\alpha$  values' existence depend on the validity of the model. It's similar to the NMF situation, where the postulate postulates existence of a set of "typical" users.

MM involves replacing both sides of an equation like (7.3) by sample estimates, in this case

$$\overline{K} = 2\widehat{r} \tag{7.4}$$

where

$$\overline{K} = \frac{K_1 + \dots + K_n}{n} \tag{7.5}$$

and  $\hat{r}$  is our estimate of  $r^2$ .

So the idea of MM is:

- 1. Find theoretical (i.e. population-level) equations for various expected values, enough to cover the number of parameters being estimated.
- 2. In those equations, replace expected values and parameters by sample estimates.
- 3. Solve for the sample estimates.

#### 7.2.2.1 The Method of Maximum Likelihood

To guess r in the game, you might ask, "What value of r would make it most likely to need 7 tosses to get r heads?" You would then find the value of w that maximizes the *likelihood*, defined to be the probability of our observed data under a given value of the parameter(s), in this case

$$\Pi_{i=1}^{n} \binom{K_{i}}{w-1} 0.5^{K_{i}} \tag{7.6}$$

In this discrete case you could not use calculus, and simply would use trial-and-error to find the maximizing value of w, which will be our  $\hat{r}$ .

#### 7.2.2.2 Comparison: MM vs. MLE

If these two methods were nervous academics, MM would be quite envious of MLE:

• MLE is by far the more widely-used method.

<sup>&</sup>lt;sup>2</sup>It is standard to use the "hat" symbol to mean "estimate of."

- MLE can be shown to be optimal in a certain sense. (Roughly, it has the smallest possible variance of all estimators, when n is large.)
- Various aspects of MLE and related topics are famous enough to be named after people, e.g. Fisher information (yes, the significance testing Fisher) and the Cramer-Rao lower bound.

On the other hand:

- Often MM makes fewer assumptions than MLE. That will be the case for us in the RS application below, a major point.
- MM is easier to explain. MLE has the same "What if...?" basis that p-values have, rather confusing.
- MM is actually the basis for the 2013 Nobel Prize in Economics! Lars Peter Hansen won the prize for his development of the Generalized Method of Moments estimation tool.

## 7.3 MM Applied to (7.1)

As you'll see, MM is arguably the more useful of the two methods in this particular setting.

#### 7.3.1 Derivation of the Estimates

The expected values in Section 7.2.2 can be conditional. So, from (7.1), write

$$E(Y_{IJ} \mid I = k) = \mu + \alpha_k + E(\beta_J \mid I = k), \ k = 1, 2, ..., u$$
(7.7)

But since I and J are independent, we have

$$E(\beta_J | I = k) = E(\beta_J) = 0, \ k = 1, 2, ..., u$$
(7.8)

 $\mathbf{SO}$ 

$$E(Y_{IJ} \mid I = k) = \mu + \alpha_k, \ k = 1, 2, ..., u$$
(7.9)

Now we must find our sample estimate of the left-hand side, and equate it to  $\mu + \alpha_k$ .

But the natural estimate of  $E(Y_{IJ} | I = k)$  is simply the mean rating user k gave to all movies she rated.

Moreover, the natural estimate of  $\mu$  is the average rating given to all movies in our data.

So we now have our  $\hat{\alpha}_k$ . The derivation of the  $\hat{\beta}_l$  is similar.

#### 7.3.2 Relation to Linear Model

For simplicity, consider the call

lm(rating  $\sim$  userID-1)

omitting the movies. Think of what will happen with the matrix A and the vector D in Section 3.4.5.

Recall that the -1 in the above call means we do not want an intercept term. In that case, Im() will produce u dummy variables rather than u - 1. This will help clarify the situation.

So, in the matrix A, column i will be the vector of 1s and 0s in the dummy for user i, i = 1, ..., u. Now consider the (i, i) element in A'A. It's the dot product of row i in A' and column i in A, thus the dot product of column i in A and column i in A. That will in turn be the sum of some 1s actually,  $n_i$  1s, where  $n_i$  is the number of ratings user i has made.

Meanwhile, the same reasoning says that for  $i \neq j$ , element (i, j) in A'A is 0, since two dummy vectors coming from the same categorical variable will never have a 1 in the same position.

Putting all that together, we have that

$$(A'A)^{-1} = \operatorname{diag}(\frac{1}{n_1}, ..., (\frac{1}{n_u})$$
(7.10)

a diagonal matrix with the indicated elements.

What about A'D in (3.4.5)? Similar reasoning shows that its  $m^{th}$  element is the sum of all the ratings given by user m.

Putting this all together, we find that the  $m^{th}$  estimated coefficient returned by lm() will be the average rating given by user m — exactly the same as MM gave us!

## 7.4 MLE Applied to (7.1)

Here, the  $\alpha$ ,  $\beta$  and  $\epsilon$  terms are assumed to have Gaussian distributions. Continue to assume they have mean 0, and denote their variances by  $\sigma_1^2$ ,  $\sigma_2^2$  and  $\sigma^2$ , respectively.

Since Gaussian distributions are continuous, the likelihood function L involves density functions rather than probabilities. L will then be a complicated expression involving various instances of the standard normal density,

$$\phi(w) = \frac{1}{\sqrt{2\pi}} e^{-0.5w^2} \tag{7.11}$$

 $\mu$ ,  $\sigma_1^2$ ,  $\sigma_2^2$ ,  $\sigma^2$ , the  $\alpha$  and  $\beta$  terms, and the user ratings. The expression is maximized with respect to  $\mu$ ,  $\sigma_1^2$ ,  $\sigma_2^2$  and  $\sigma^2$ , to obtain the corresponding estimates. Of course, an iterative procedure is used for the maximization.

What, then, do we get from this?

- We get predicted values for all user/movie combinations, as with MM.
- We get estimates of the  $\sigma_i^2$ , of interest as we can tell whether there is more variation in users or in movies or maybe not much in either, so we can't expect to predict well.<sup>3</sup>
- On the other hand, the Gaussian assumption is extremely strong, especially in view of the fact that ratings (in this case) are integers from 1 to 5.

### 7.5 Conclusion

MM seems a better bet here. It makes fewer restrictive assumptions, it is fast computationally, and jibes with an lm() analysis.

 $<sup>^{3}\</sup>mathrm{It}$  is possible to get variance estimates using MM as well.